

Instrument Flight Procedure data set

CGX Proposal of Coding Guidelines

*INTERREGIONAL EUR/MID WORKSHOP ON AERONAUTICAL
INFORMATION DATASETS*

Cairo, Egypt 21-22 may 2023



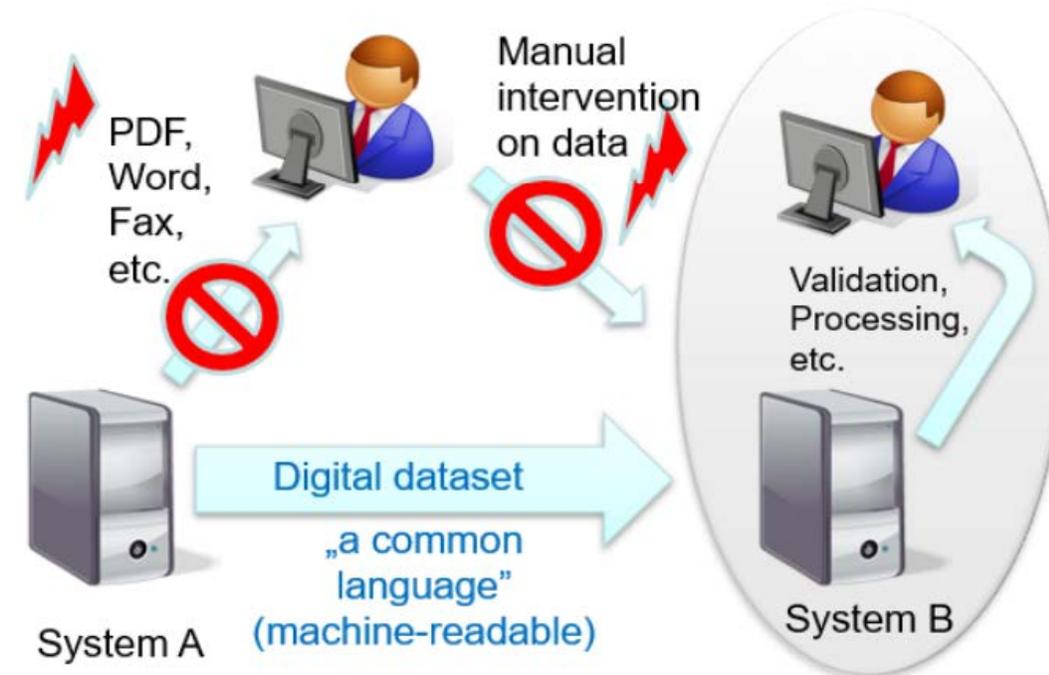
PRESENTATION'S SUMMARY

- **Digital data sets introduction**
- **PANS AIM mapping to AIXM 5.2**
- **Coding Guidelines**
- **Coding examples**
- **Application with CGX solutions**



Context & Goals

- » Digital data sets are one of the pillar of the AIS to AIM transition
- » Required to build seamless aeronautical information
- » Needed to:
 - Replace gradually the provision of paper documents
 - Standardize format and structure
 - Ensure minimum set of provided information
 - Facilitate communication of information between stakeholders
 - Facilitate the definition of Data Quality Requirements

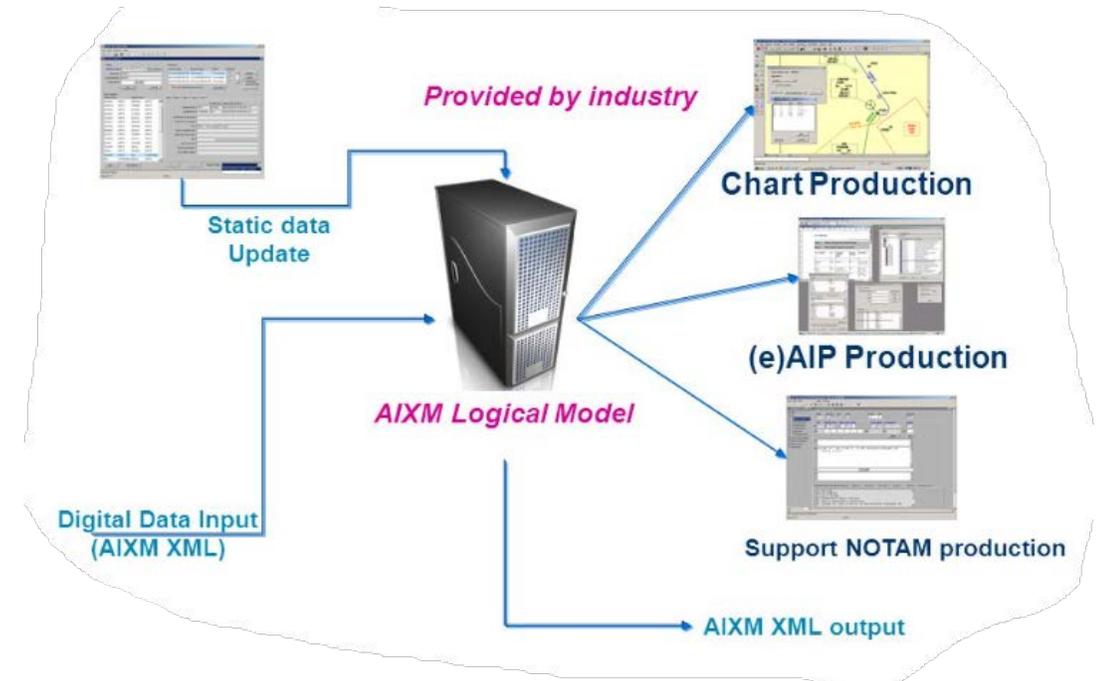




Digital data sets introduction

Advantages

- » Aeronautical information will include **Temporality** concept
- » Digital data sets will provide **Meta Data**
- » Data verification will be possible thanks to **Business Rules**
- » Data integrity will be ensured using the **CRC**
- » Digital data sets will help to be **SWIM** ready
- » Digital data sets will help to be **Digital NOTAM** ready





Digital data sets introduction

Defaults of current navigation databases

- » Different non structured formats are used
 - Navigation databases are mainly derived from a copy of the AIP, providing rounded and/or truncated data compared to the source data available in the various technical departments of civil aviation
- » Data Quality Requirements are not respected
 - The limitations of certain FMS lead to the need for data alteration to allow to fly the procedures
 - Loss of precision between the initial design and what goes on board the planes
- » Different data bases are used
- » Aeronautical information are not centralized
- » No harmonization between civilians and military
- » No dedicated workflows



Digital data sets : Context & Goals

IFP Dataset added value

- » Part of the AIM chain
 - required for charting and Navigation Databases
 - Increase the integrity of the chain, in particular **AIS** → **navDB provider**.
- » The AIS could monetize their data more easily **vs** Today business is concentrated = the navDB provider level
- » A real time saving and quality improvement of procedure designer daily work:
 - Procedure maintenance
 - Procedure update against new obstacles
 - Technical report automation
 - Automatic generation of ARINC 424 coding
- » Automatic Charting, in direct connection with central database
- » Procedure digital dataset could bring new uses of the data (provision of protection areas for obstacles creators)
- » Possibility to implement Ground Validation tools

PANS AIM mapping to AIXM 5.2





PANS AIM mapping to AIXM 5.2

IFP Dataset – PANS AIM minimum data items

The instrument flight procedure data set **shall** include data as a **minimum** :

- a) procedure
- b) procedure segment
- c) final approach segment
- d) procedure fix
- e) procedure holding
- f) helicopter procedure

The IFP data set **should** include the requirements for data publication contained in **PANS-OPS, Doc. 8168, Volume II**

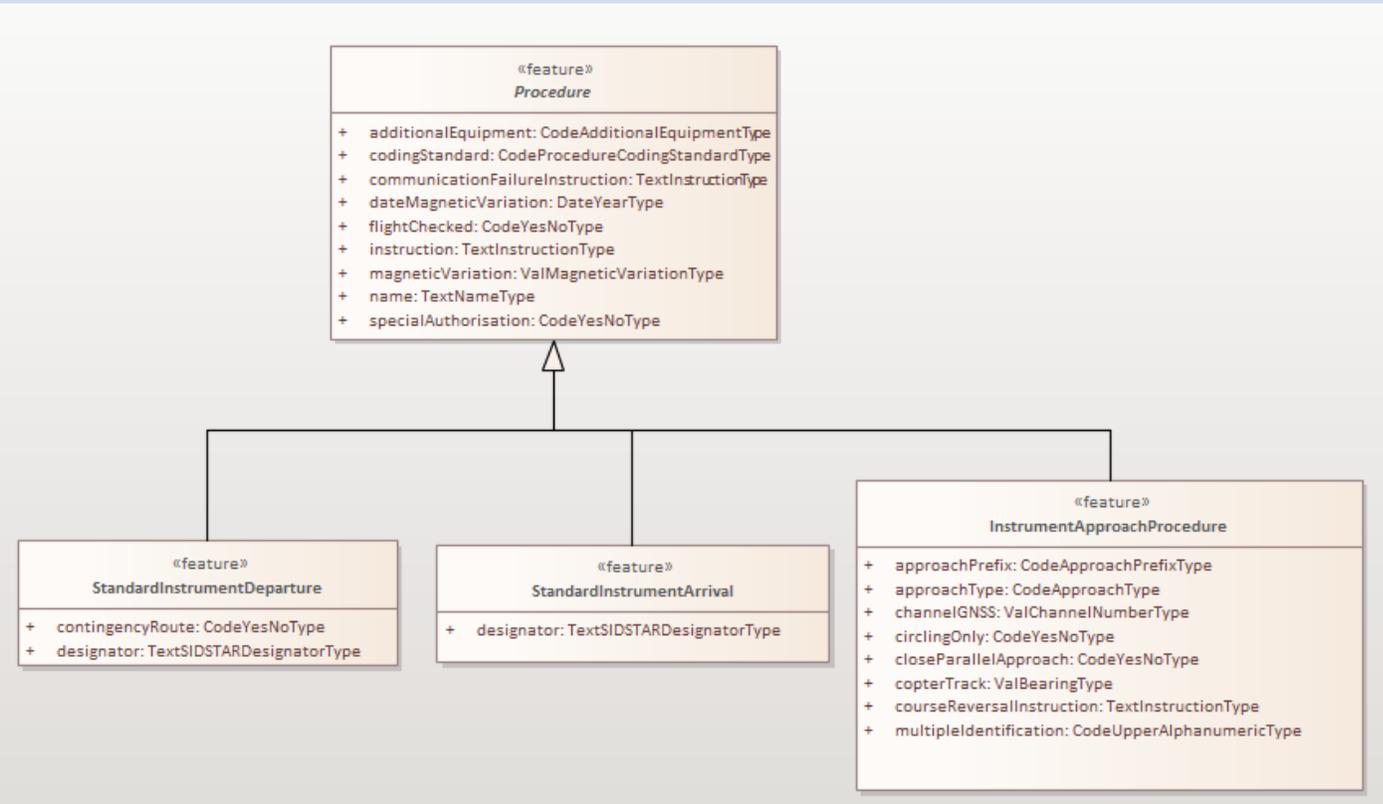
PANS AIM mapping to AIXM 5.2

Mapping PANS AIM to AIXM 5.2 - Procedure

PANS AIM

Subject	Property	Sub-Property
Procedure		
	Identification	FAS Guidance
		Runway
		Circling
		Multiple Code
		NS Limiter
		Name
	Plain Language Designation	Basic Indicator
		Validity Indicator
		Route Indicator
		Visual Indication
	Coded Designation	Significant Point
		Validity Indicator
		Route Indicator
	Procedure Type	
	PBN or Conventional	

AIXM 5.2





PANS AIM mapping to AIXM 5.2

Mapping PANS AIM to AIXM 5.2 – Procedure : **Partial view**

PANS AIM	AIXM 5.2
Identification – FAS Guidance	Procedure.GuidanceService.navaid.type
Identification – Runway	Procedure.AirportHeliport.Runway.designator
Identification – Circling	InstrumentApproachProcedure.circlingOnly (AIXM 5.2)
Identification – Multiple Code	InstrumentApproachProcedure.multipleIdentification
Identification – Name	Procedure.name
Procedure Type	StandardInstrumentDeparture StandardInstrumentArrival InstrumentApproachProcedure.
PBN or Conventional	Procedure.AircraftCharacteristic.navigationType
Precision Type	InstrumentApproachProcedure.FinalLeg. ApproachCondition.landingPrecisionCategory (AIXM 5.2)
Aircraft Category	Procedure.AircraftCharacteristic.aircraftLandingCategory
Magnetic variation	Procedure.magneticVariation

AIXM 5.2 specific planned : procedures

- Identification – Circling
- Approach precision « Precision Type »

PANS AIM mapping to AIXM 5.2

➤ Mapping PANS AIM to AIXM 5.2 – Procedure Segment

PANS AIM		AIXM 5.2	
Subject	Property	Sub-Property	
Procedure Segment			
	Start		
	End		
	End fix functionality		
	End fix role		
	Procedure altitude/height		
	MOCA		
	Distance		
	True bearing		
	Magnetic bearing		
	Gradient		
	Speed		
	Controlling obstacle		
		Type	
		Position	
		Elevation:	

«feature»
SegmentLeg

- + additionalEquipment: CodeAdditionalEquipmentType
- + altitudeOverrideATC: ValDistanceVerticalType
- + altitudeOverrideReference: CodeVerticalReferenceType
- + bankAngle: ValAngleType
- + duration: ValDurationType
- + endConditionDesignator: CodeSegmentTerminationType
- + legPath: CodeTrajectoryType
- + legTypeARINC: CodeSegmentPathType
- + length: ValDistanceType
- + lowerLimit: ValDistanceVerticalType
- + lowerLimitReference: CodeVerticalReferenceType
- + minimumObstacleClearanceAltitude: ValDistanceVerticalType
- + minimumObstacleClearanceHeight: ValDistanceVerticalType
- + procedureTurnRequired: CodeYesNoType
- + radius: ValDistanceType
- + speedInterpretation: CodeSpeedInterpretationUseType
- + speedLimit: ValSpeedType
- + speedReference: CodeSpeedReferenceType
- + turnDirection: CodeDirectionTurnType
- + upperLimit: ValDistanceVerticalType
- + upperLimitReference: CodeVerticalReferenceType
- + verticalAngle: ValAngleType
- + verticalLimitsInterpretation: CodeAltitudeUseType

```

classDiagram
    class SegmentLeg["«feature» SegmentLeg"]
    class ApproachLeg["«feature» ApproachLeg"]
    class DepartureLeg["«feature» DepartureLeg"]
    class ArrivalLeg["«feature» ArrivalLeg"]
    SegmentLeg <|-- ApproachLeg
    SegmentLeg <|-- DepartureLeg
    SegmentLeg <|-- ArrivalLeg
            
```



PANS AIM mapping to AIXM 5.2

Mapping PANS AIM to AIXM 5.2 – Procedure Segment : **Partial view**

PANS AIM	AIXM 5.2
Start	SegmentLeg.startPoint.SegmentPoint.DesignatedPoint.designator Or SegmentLeg.startPoint.SegmentPoint.Navaid.designator Or SegmentLeg.startPoint.SegmentPoint.RunwayCentrelinePoint.designator Or SegmentLeg.startPoint.SegmentPoint.TouchDownLiftOff.designator Or SegmentLeg.startPoint.SegmentPoint.AirportHeliport.designator
End	SegmentLeg.endPoint.SegmentPoint.DesignatedPoint.designator Or SegmentLeg.endPoint.SegmentPoint.Navaid.designator Or SegmentLeg.endPoint.SegmentPoint.RunwayCentrelinePoint.designator Or SegmentLeg.endPoint.SegmentPoint.TouchDownLiftOff.designator Or SegmentLeg.endPoint.SegmentPoint.AirportHeliport.designator
End fix functionality	SegmentLeg.endPoint.SegmentPoint.flyOver
End fix role	SegmentLeg.endPoint.TerminalSegmentPoint.role
Procedure altitude/height	SegmentLeg.lowerLimit
MOCA	SegmentLeg.minimumObstacleClearanceAltitude (AIXM 5.2)
Distance	SegmentLeg.length
True bearing /Magnetic bearing	SegmentLeg.CourseGroup.course and SegmentLeg.CourseGroup.courseType (AIXM 5.2)
Speed	SegmentLeg.SpeedLimit
Controlling obstacle	SegmentLeg.ObstacleAssessmentArea.Obstruction.VerticalStructure

AIXM 5.2 specific planned : Procedure Segment

- MOCA
- True bearing /Magnetic bearing

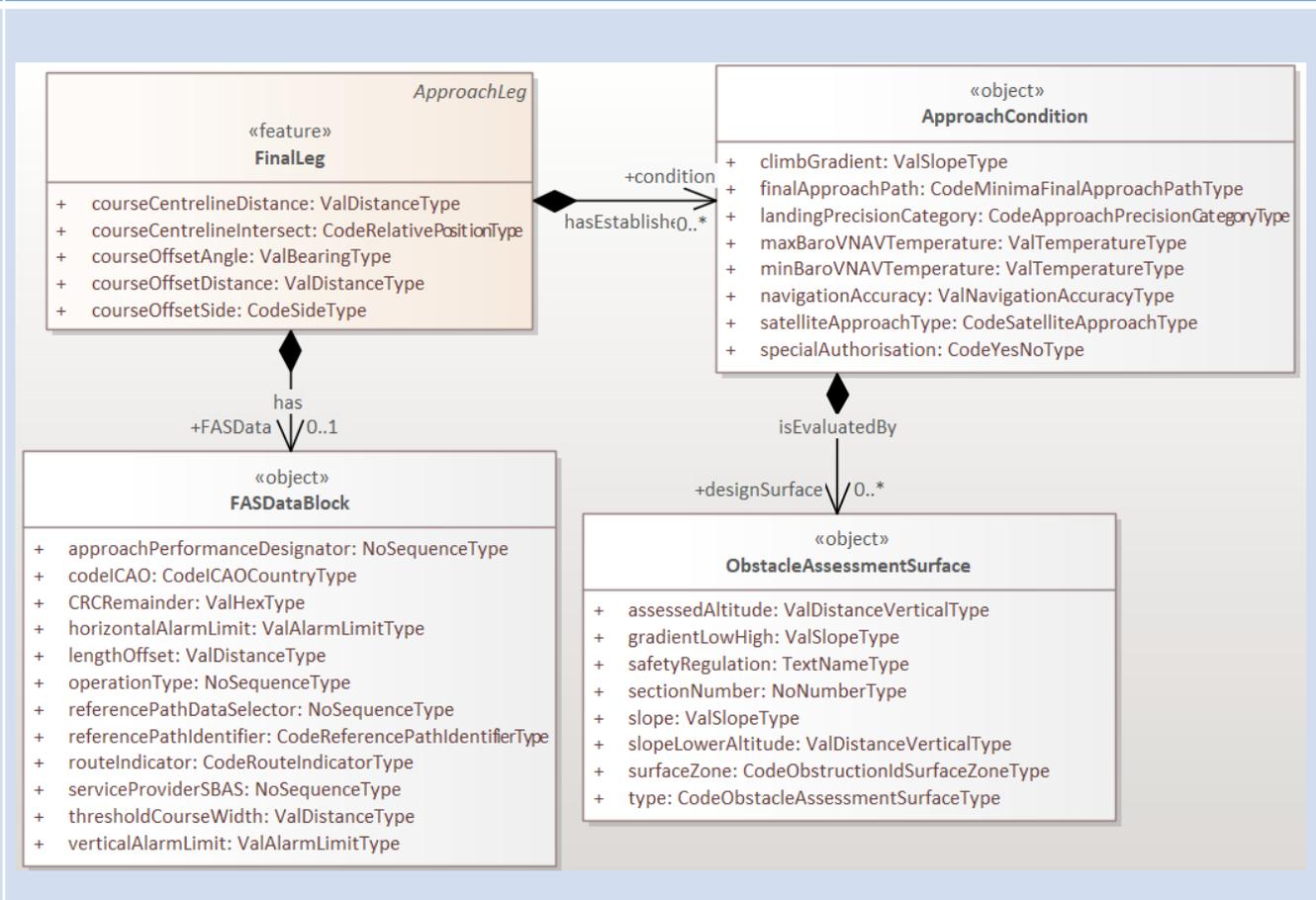
PANS AIM mapping to AIXM 5.2

Mapping PANS AIM to AIXM 5.2 – Final Approach Segment

PANS AIM

Subject	Property	Sub-Property
Final Approach Segment		
	Operation type	
	Approach performance designator	
	SBAS provider	
	RPDS	
	RPI	
	LTP/FTP	
		Position
		Ellipsoid height
		Orthometric height
	FPAP	
		Position
		Orthometric height

AIXM 5.2





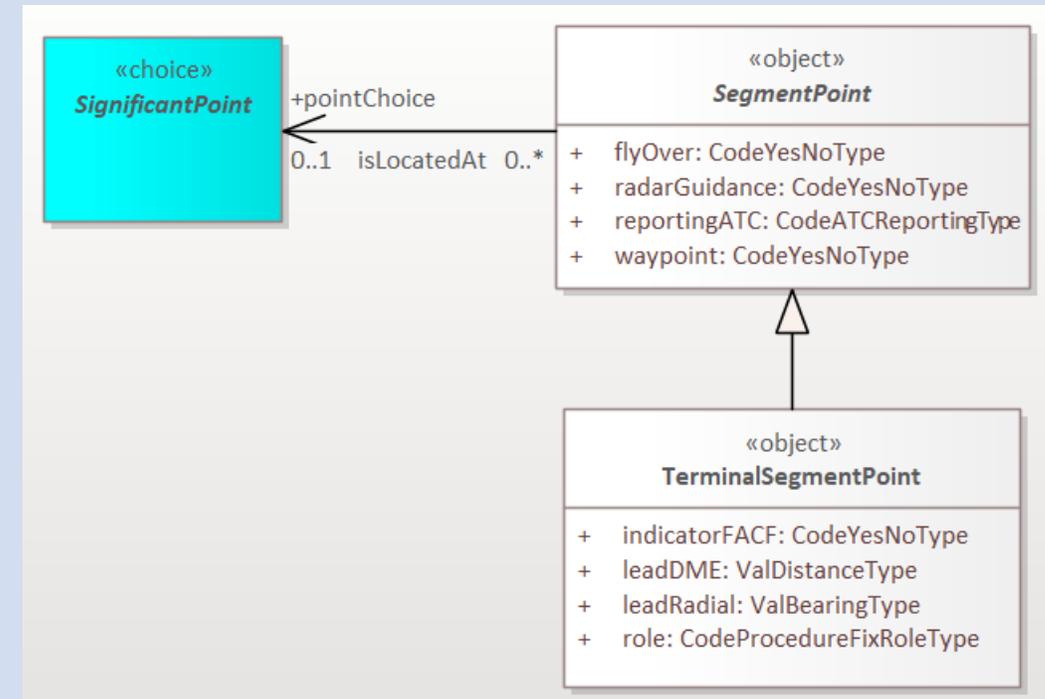
PANS AIM mapping to AIXM 5.2

» Mapping PANS AIM to AIXM 5.2 – Procedure Fix

PANS AIM

Subject	Property	Sub-Property
Procedure Fix		
	Identification	
	ATC Reporting requirements	
	VFR Reporting point	
	Position	
	Type	
	Formations	
		Navaid
		Bearing
		Distance

AIXM 5.2



PANS AIM mapping to AIXM 5.2

» Mapping PANS AIM to AIXM 5.2 – Procedure Holding

PANS AIM			AIXM 5.2		
Subject	Property	Sub-Property			
Procedure Holding					
	Identification		<pre> classDiagram class HoldingPattern { <<feature>> + instruction: TextInstructionType + lowerLimit: ValDistanceVerticalType + lowerLimitReference: CodeVerticalReferenceType + nonStandardHolding: CodeYesNoType + speedLimit: ValSpeedType + turnDirection: CodeDirectionTurnType + type: CodeHoldingUsageType + upperLimit: ValDistanceVerticalType + upperLimitReference: CodeVerticalReferenceType } class SegmentPoint { <<object>> + flyOver: CodeYesNoType + radarGuidance: CodeYesNoType + reportingATC: CodeATCReportingType + waypoint: CodeYesNoType } class HoldingPatternLength { <<choice>> } class HoldingPatternDistance { <<object>> + length: ValDistanceType } class HoldingPatternDuration { <<object>> + duration: ValDurationType } HoldingPattern *-- SegmentPoint : isBasedOn HoldingPattern *-- HoldingPatternLength : +outboundLegSpan HoldingPatternLength --> HoldingPatternDistance : hasSpan 0..* HoldingPatternLength --> HoldingPatternDuration : hasSpan 0..* </pre>		
	Fix				
	Inbound course				
	Outbound course				
	Leg distance				
	Leg time				
	Limiting radial				
	Turn direction				
	Minimum altitude				
	Maximum altitude				

Coding Guidelines

CGX proposal





Coding Guidelines

CGX Approach

State of the art

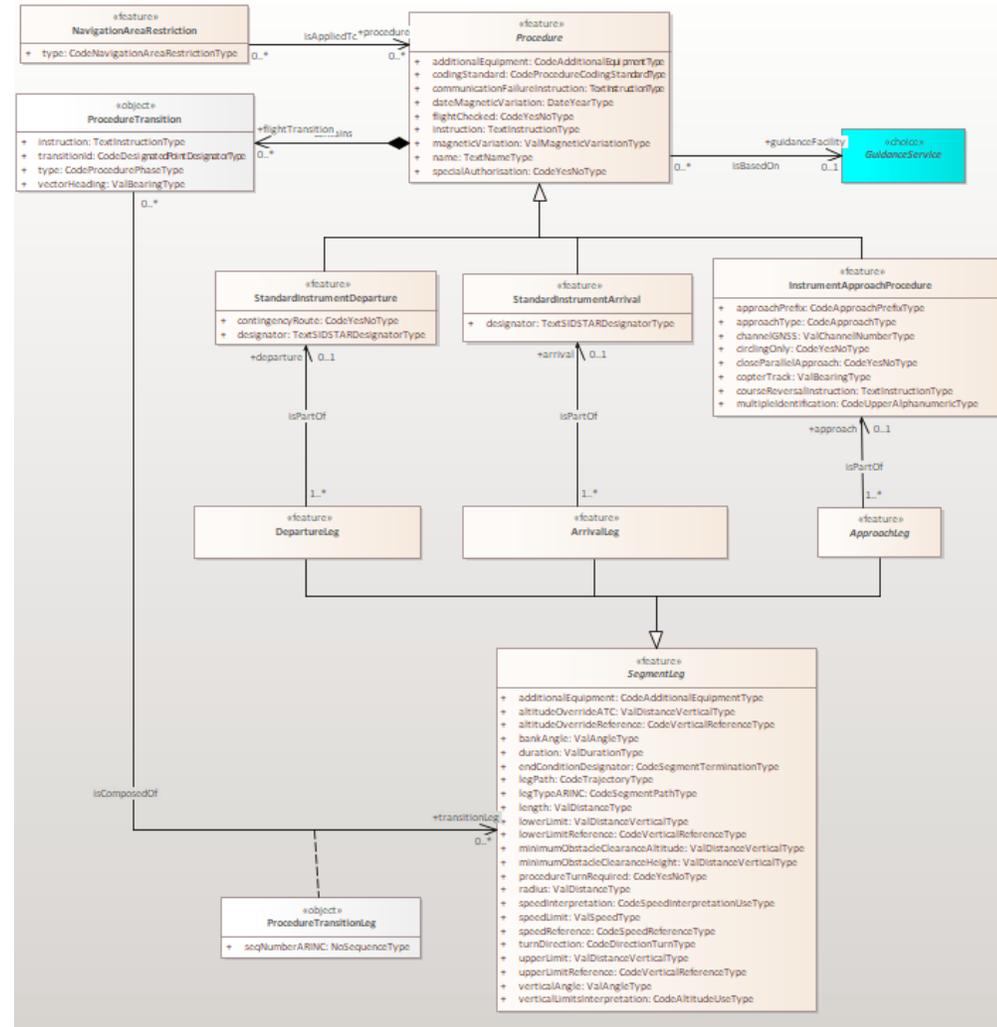
- EUROCONTROL provides a proposition of coding specifications for various aeronautical information products and services.
- AIXM Coding Guidelines are proposed for the following specific products:
 - (ICAO) AIP Data Set
 - (ICAO) Obstacle Data Sets
 - (ICAO) Airport Mapping Data Sets
 - Digital NOTAM
- The coding guidelines for IFP data sets are being developed in parallel with the finalization of AIXM 5.2 → **Not yet available on EUROCONTROL AIXM Confluence**

CGX Approach

- Similar work to the available Data Set Coding Specifications in the products
- Proposal of some coding guidelines
- Proposal of examples for IFP data sets.

Coding Guidelines

» Procedure Coding Guidelines – AIXM Model overview





Coding Guidelines

Procedure Coding Guidelines – CGX AERO proposal

1. The main class in IFP AIXM model is the Procedure class containing the basic data, such as the name of the procedure.
2. In AIXM 5, the Procedure is defined as “A series of predetermined manoeuvres with specified protection from obstacles.”
3. The Procedure may serve one or more AirportHeliport.
4. The standard design rules and criteria for the procedure are defined in DesignStandard, with the attributes Name and Version.
5. The Procedure may be limited to one or more AircraftCharacteristic, which defines the Classification, properties, and equipment capabilities of aircraft, such as airplane, balloon, helicopter, etc.
6. The Procedure may be based on one or more GuidanceService as a guidance facility, which may be a Navaid, a SpecialNavigationSystem, a GBAS, a SatelliteSystem or a RadarSystem.



Coding Guidelines

» Procedure Coding Guidelines

7. The Procedure may be applied to one or more NavigationAreaRestriction, Areas that are restricted from use for a procedure.
8. The Procedure may be protected by one or more MinimumAltitudeArea.
9. The availability of the Procedure, such as the status for flight planning/operations, may be provided via the ProcedureAvailability and its related classes.
10. The Procedure class is specialized into: StandardInstrumentDeparture, StandardInstrumentArrival and InstrumentApproachProcedure.
11. The StandardInstrumentDeparture and StandardInstrumentArrival are used to code departure and arrival procedures, which are identified by their designator (e.g 'KOGAL1A').



Coding Guidelines

» Procedure Coding Guidelines

12. The [InstrumentApproachProcedure](#) is used to code approach procedure, it contains specific attributes such as [approachPrefix](#), [approachType](#) and [multipleIdentification](#).
13. The [LandingTakeoffAreaCollection](#) groups Landing Areas or Takeoff Areas serviced by the procedure, Arrival for STAR, Take off for SID and Landing for IAP procedures. It may be located on one or more [RunwayDirection](#), or [TouchDownLiftOff](#) for helicopters.
14. When an approach cannot be continued, missed instructions may be defined in [MissedApproachGroup](#) associated to the [InstrumentApproachProcedure](#).
15. The [FinalProfile](#) defines the profile view of an [InstrumentApproachProcedure](#). Altitudes and distances to be depicted in the profile view may be defined using [ApproachAltitudeTable](#) and [ApproachDistanceTable](#). In addition, timings between final approach fix and the missed approach point may be defined using [ApproachTimingTable](#).



Coding Guidelines

» Procedure Coding Guidelines

16. One or more CirclingArea may be used for an InstrumentApproachProcedure, allowing to land under visual conditions after completing an instrument landing approach.
17. The lowest altitudes providing the minimum clearances may be defined in one or more TerminalArrivalArea associated to the InstrumentApproachProcedure.
18. The Procedure contains one or more ProcedureTransition, which is a group of consecutive segments that are part of a branch on an approach procedure, SID or STAR.

Coding Examples

CGX Proposition



Coding Example

Procedure Coding Example

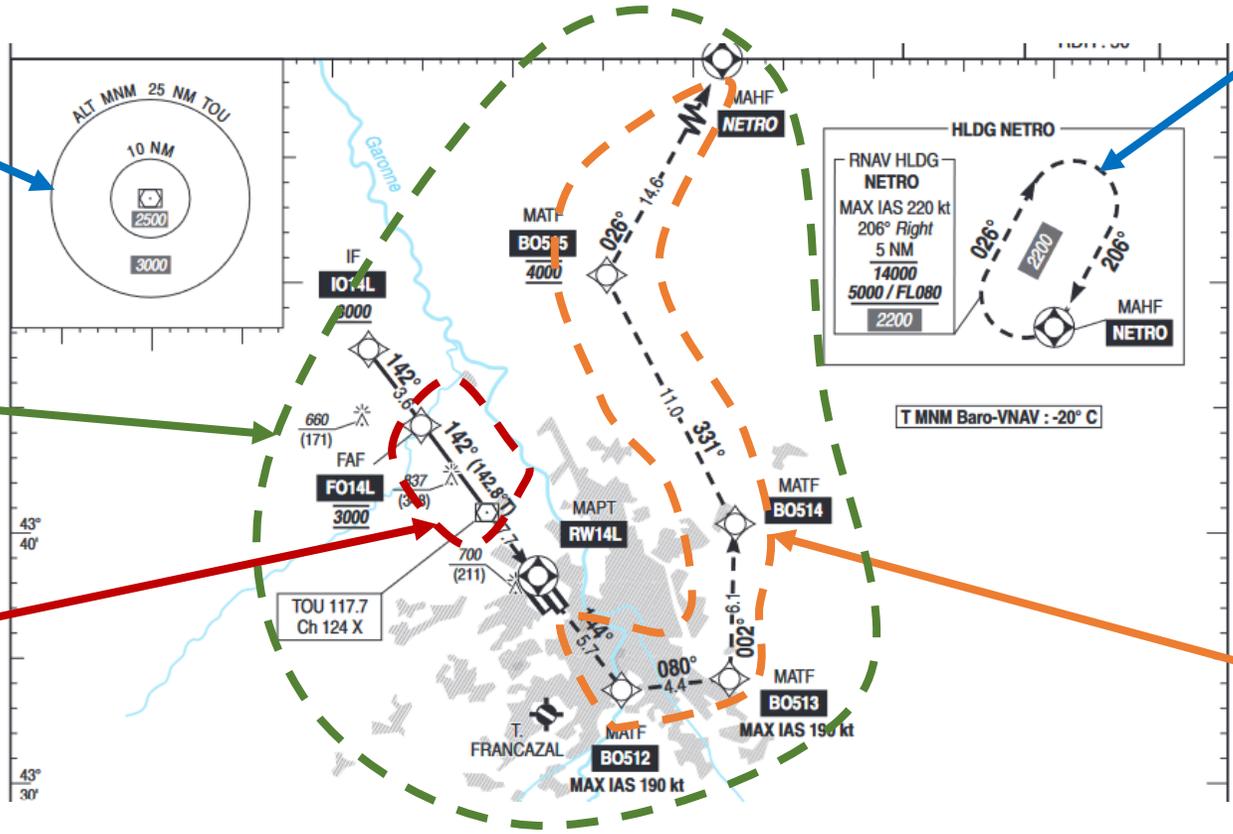
MinimumAltitudeArea
 Defines the minimum altitudes for specific flight operations

InstrumentApproachProcedure
 Defines the manoeuvres for the approach flight procedure from the initial approach fix or an arrival route

FinalLeg
 Defines the properties of final approach segment

HoldingPattern
 Defines the properties of manoeuvre keeping aircraft awaiting further clearance

ProcedureTransition
 Missed approach branch, defined by transition id and type



Coding Example

» Procedure Coding Example

FNA RNP RWY 32L												
RMK								MAG VAR 2020 01.0°E			REF NAVAID :	
Leg sequence	Path Terminator	Waypoint Identification	Fly Over	Direction MAG (°)	Direction True (°)	Distance (NM)	Turn direction	MNM Altitude (FL or AMSL ft)	MAX Altitude (FL or AMSL ft)	MAX IAS (kt)	Vertical angle (°) / TCH (m)	NAV Spec
HLDG	-	SULIT	Yes	007	007.9	5.0	R	FL080 /5000	FL140	220	-	RNAV1 / RNP APCH
APCH	IF	IO32L	-	-	-	-	-	3000	-	-	-	RNP APCH
	TF	FO32L	-	322	323.0	3.6	-	3000	3000	-	-	RNP APCH
	TF	RW32L	Yes	322	323.0	7.7	-	-	-	-	-3.0 / 15	RNP APCH
	TF	TOU	Yes	323	323.8	4.6	-	-	-	-	-	RNP APCH
	TF	BO614	-	303	304.0	10.0	L	-	4000	-	-	RNP APCH
	TF	BO616	-	250	251.0	10.1	L	-	-	-	-	RNP APCH
	TF	BO618	-	165	166.4	13.9	L	-	-	-	-	RNP APCH
TF	SULIT	Yes	118	118.5	13.8	-	-	-	-	-	RNP APCH	

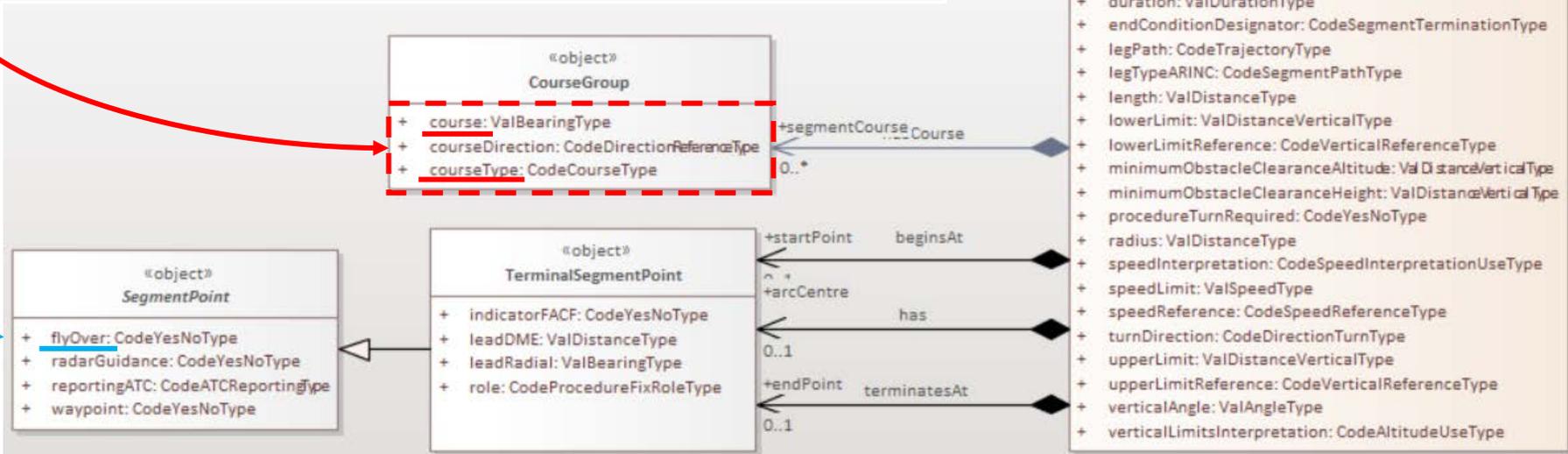
«feature»
SegmentLeg

- + additionalEquipment: CodeAdditionalEquipmentType
- + altitudeOverrideATC: ValDistanceVerticalType
- + altitudeOverrideReference: CodeVerticalReferenceType
- + bankAngle: ValAngleType
- + duration: ValDurationType
- + endConditionDesignator: CodeSegmentTerminationType
- + legPath: CodeTrajectoryType
- + legTypeARINC: CodeSegmentPathType
- + length: ValDistanceType
- + lowerLimit: ValDistanceVerticalType
- + lowerLimitReference: CodeVerticalReferenceType
- + minimumObstacleClearanceAltitude: ValDistanceVerticalType
- + minimumObstacleClearanceHeight: ValDistanceVerticalType
- + procedureTurnRequired: CodeYesNoType
- + radius: ValDistanceType
- + speedInterpretation: CodeSpeedInterpretationUseType
- + speedLimit: ValSpeedType
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- + turnDirection: CodeDirectionTurnType
- + upperLimit: ValDistanceVerticalType
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- + verticalLimitsInterpretation: CodeAltitudeUseType

Coding Example

➤ Procedure Coding Example

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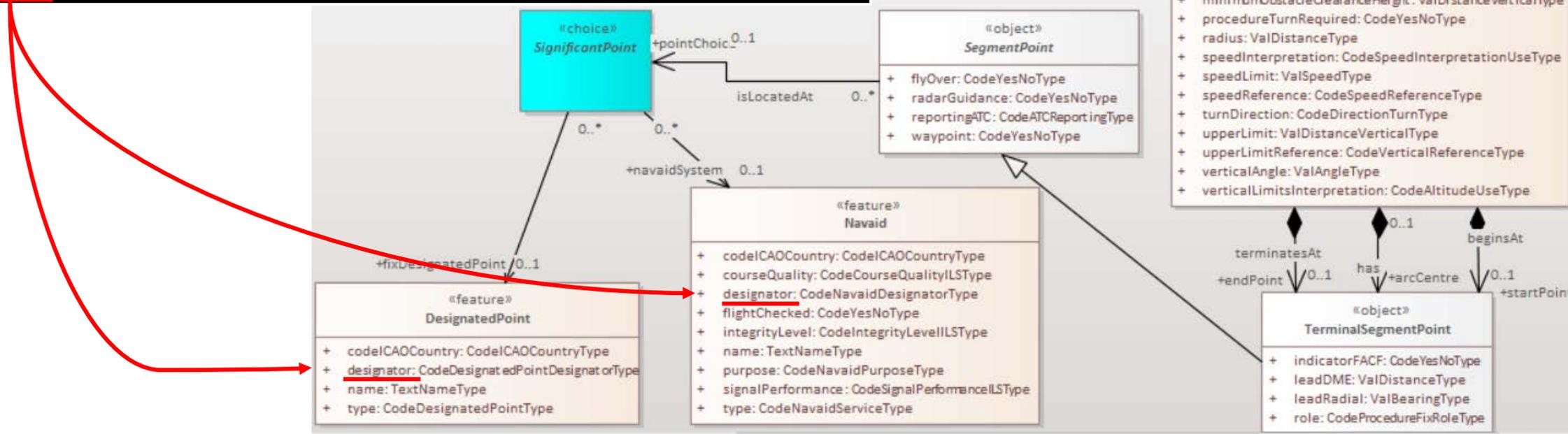
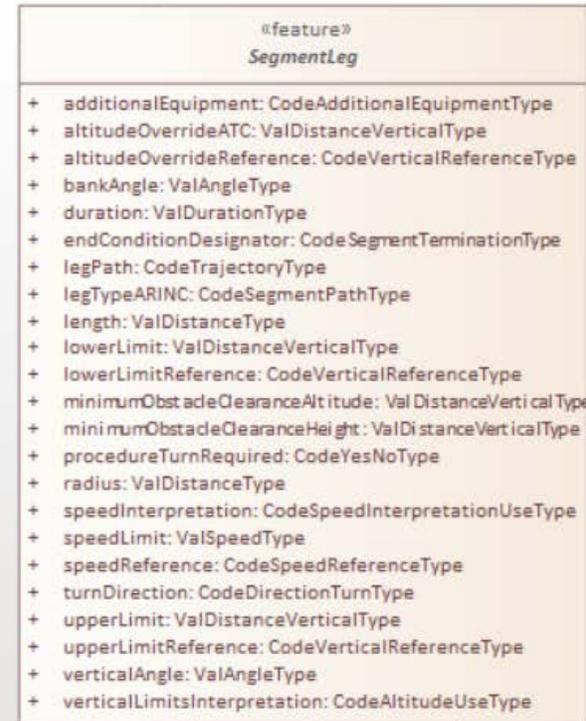


- «feature» SegmentLeg
- + additionalEquipment: CodeAdditionalEquipmentType
 - + altitudeOverrideATC: ValDistanceVerticalType
 - + altitudeOverrideReference: CodeVerticalReferenceType
 - + bankAngle: ValAngleType
 - + duration: ValDurationType
 - + endConditionDesignator: CodeSegmentTerminationType
 - + legPath: CodeTrajectoryType
 - + legTypeARINC: CodeSegmentPathType
 - + length: ValDistanceType
 - + lowerLimit: ValDistanceVerticalType
 - + lowerLimitReference: CodeVerticalReferenceType
 - + minimumObstacleClearanceAltitude: ValDistanceVerticalType
 - + minimumObstacleClearanceHeight: ValDistanceVerticalType
 - + procedureTurnRequired: CodeYesNoType
 - + radius: ValDistanceType
 - + speedInterpretation: CodeSpeedInterpretationUseType
 - + speedLimit: ValSpeedType
 - + speedReference: CodeSpeedReferenceType
 - + turnDirection: CodeDirectionTurnType
 - + upperLimit: ValDistanceVerticalType
 - + upperLimitReference: CodeVerticalReferenceType
 - + verticalAngle: ValAngleType
 - + verticalLimitsInterpretation: CodeAltitudeUseType

Coding Example

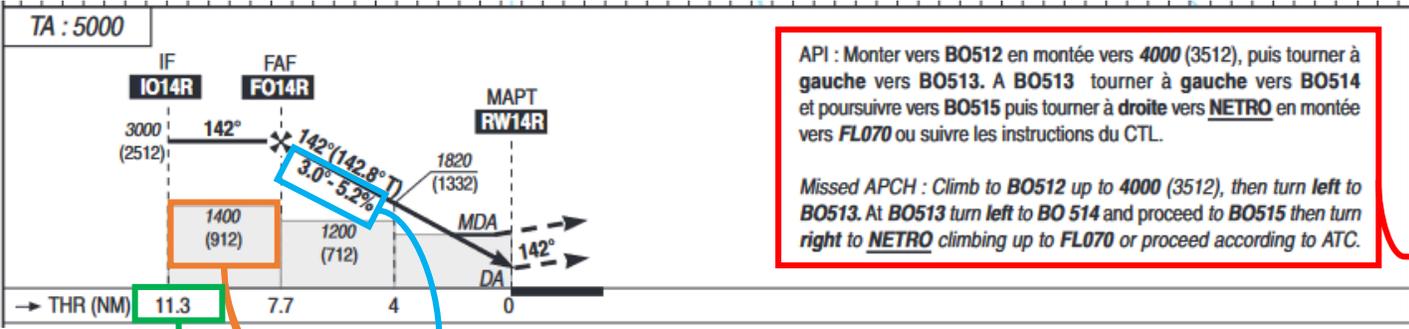
➤ Procedure Coding Example

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RMK								MAG VAR 2020	01.0°E	REF NAVAID :		
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TF	SULIT	Yes	118	118.5	13.8	-	-	-	-	-	RNP APCH	



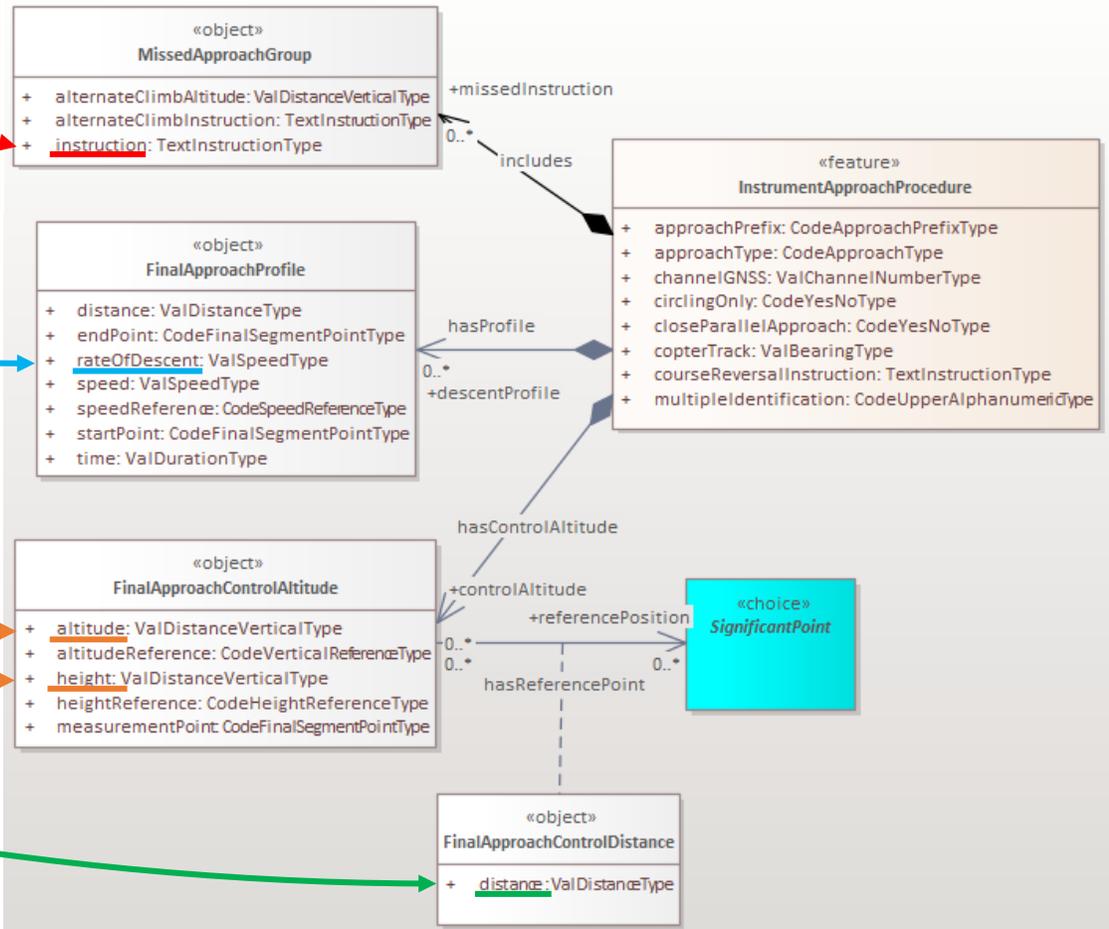
Coding Example

➤ Procedure Coding Example



API : Monter vers BO512 en montée vers 4000 (3512), puis tourner à gauche vers BO513. A BO513 tourner à gauche vers BO514 et poursuivre vers BO515 puis tourner à droite vers NETRO en montée vers FL070 ou suivre les instructions du CTL.

Missed APCH : Climb to BO512 up to 4000 (3512), then turn left to BO513. At BO513 turn left to BO 514 and proceed to BO515 then turn right to NETRO climbing up to FL070 or proceed according to ATC.



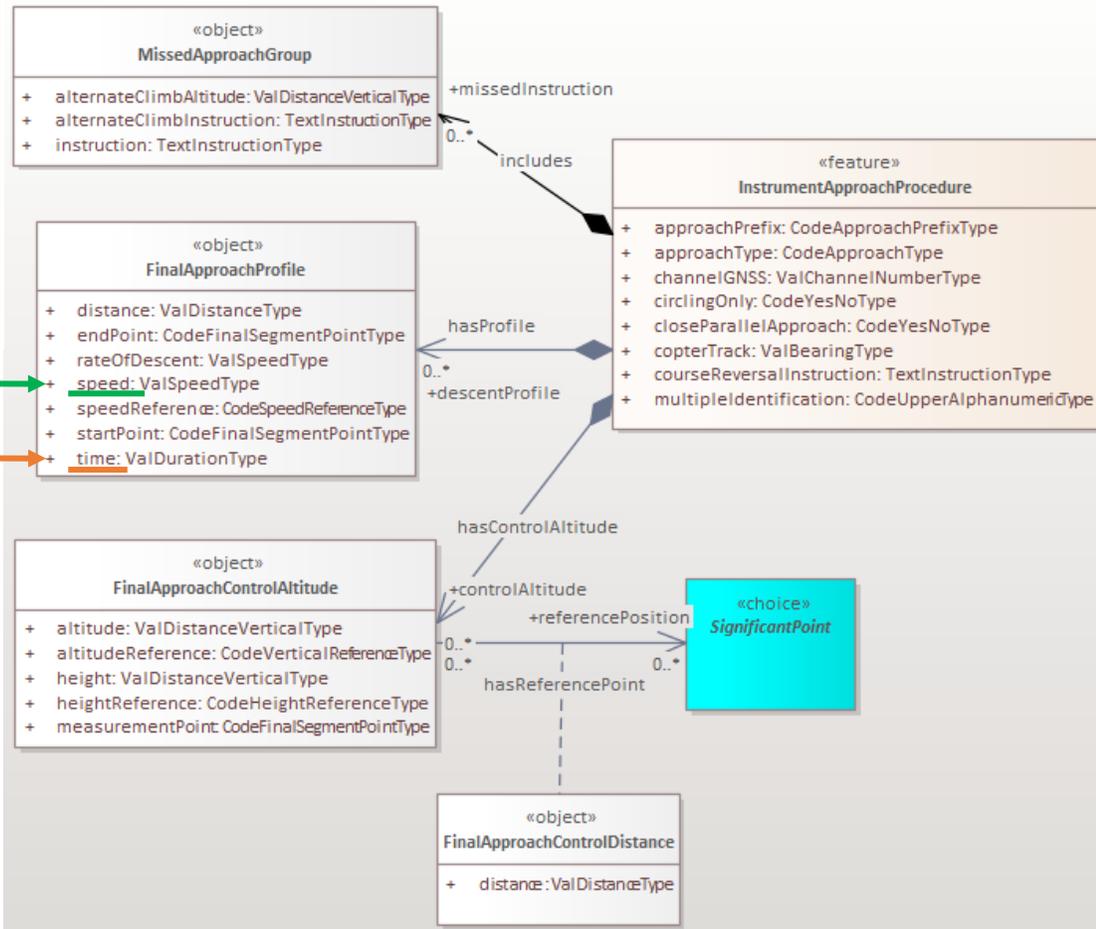


Coding Example

» Procedure Coding Example

→ THR (NM) 11.3 7.7 4 0											
MNM AD : distances verticales en pieds, RVR et VIS en mètres / vertical distances in feet, RVR and VIS in metres.											
CAT	LPV			LNAV/VNAV			LNAV			MVL / Circling	DIST RW14R
	DA (H)	RVR	OCH	DA (H)	RVR	OCH	MDA (H)	RVR	OCH	MDA (H)	
A	740 (250)	750	220							1030 (530)	1500
B	740 (250)	750	230	900 (410)	1200	405	950 (460)	1400	458	1050 (550)	1600
C	750 (270)	750	261							1220 (730)	2400
D	760 (280)	750	271							1320 (830)	3600
DL	770 (280)	750	280								

Observations/Remarks : (1) MVL interdites au Nord-Est de la piste / Circling prohibited North-East of RWY. Panne de guidage GNSS durant l'approche / GNSS guidance loss during approach : voir/see AIP ENR 1.5.										
FAF - RW14R	7.71 NM	70 kt	85 kt	100 kt	115 kt	130 kt	160 kt	185 kt		
VSP (ft/min)	400	6 min 36	5 min 26	4 min 37	4 min 01	3 min 33	2 min 53	2 min 30		

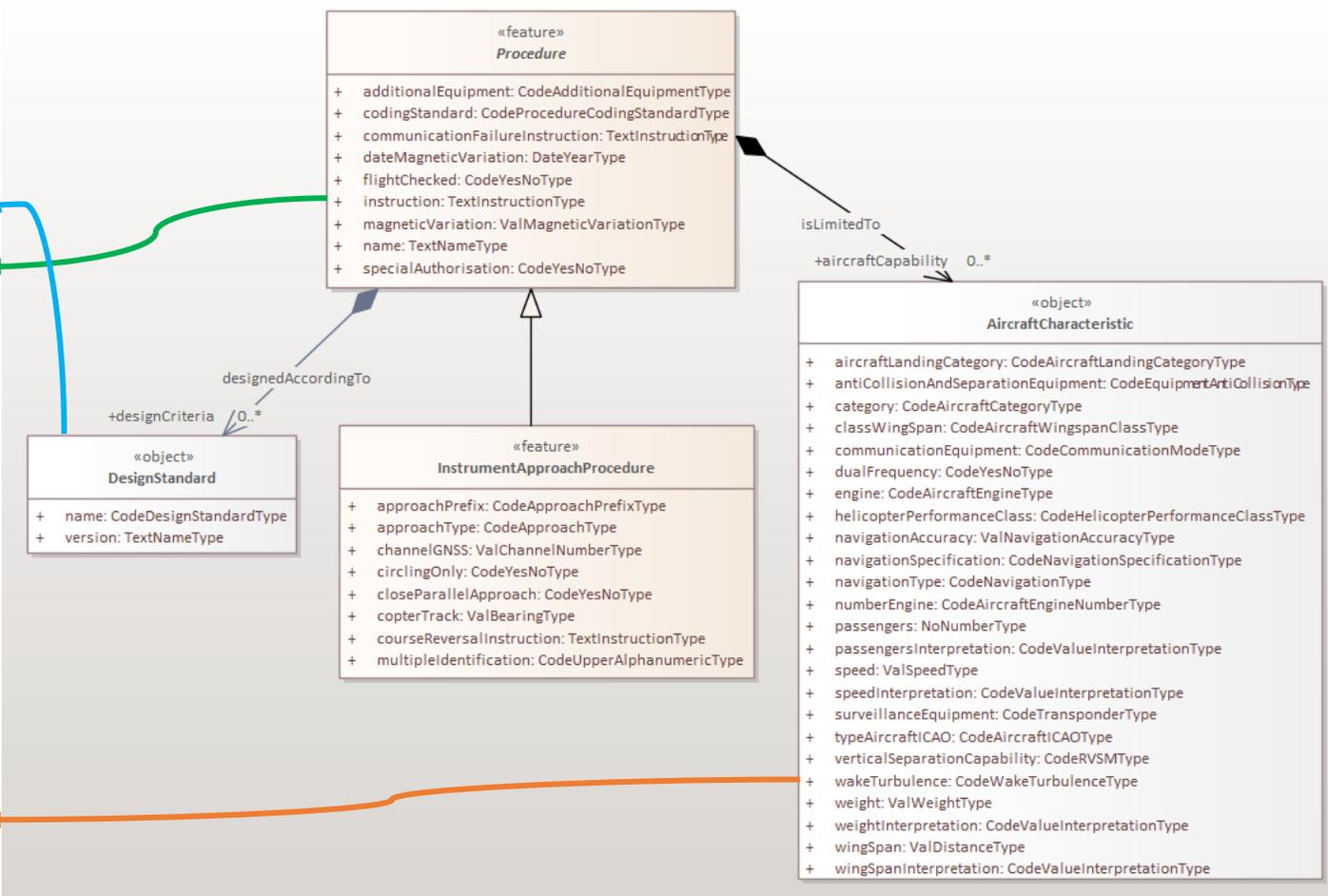


Coding Example

» Procedure Coding Example

```

<aixm:InstrumentApproachProcedureTimeSlice gml:id="SKDB_AIXM51_ENTITY_01">
  <gml:validTime>
    <gml:TimePeriod gml:id="SKDB_AIXM51_ENTITY_02_VALIDTIME">
      <gml:beginPosition>2023-05-18T00:00:00Z</gml:beginPosition>
      <gml:endPosition indeterminatePosition="unknown" />
    </gml:TimePeriod>
  </gml:validTime>
  <aixm:interpretation>BASELINE</aixm:interpretation>
  <aixm:sequenceNumber>1</aixm:sequenceNumber>
  <aixm:designCriteria>PANS OPS</aixm:designCriteria>
  <aixm:codingStandard>ARINC_424_18</aixm:codingStandard>
  <aixm:name>MEXRNAV</aixm:name>
  <aixm:RNAV>YES</aixm:RNAV>
  <aixm:aircraftCharacteristic>
    <aixm:AircraftCharacteristic gml:id="SKDB_AIXM51_ENTITY_03">
      <aixm:aircraftLandingCategory>A</aixm:aircraftLandingCategory>
    </aixm:AircraftCharacteristic>
    <aixm:AircraftCharacteristic gml:id="SKDB_AIXM51_ENTITY_04">
      <aixm:aircraftLandingCategory>B</aixm:aircraftLandingCategory>
    </aixm:AircraftCharacteristic>
    <aixm:AircraftCharacteristic gml:id="SKDB_AIXM51_ENTITY_05">
      <aixm:aircraftLandingCategory>C</aixm:aircraftLandingCategory>
    </aixm:AircraftCharacteristic>
    <aixm:AircraftCharacteristic gml:id="SKDB_AIXM51_ENTITY_06">
      <aixm:aircraftLandingCategory>D</aixm:aircraftLandingCategory>
    </aixm:AircraftCharacteristic>
  </aixm:aircraftCharacteristic>
</aixm:InstrumentApproachProcedureTimeSlice>
  
```



Application with CGX solutions





Application with CGX solutions

» Procedure ARINC 424 Coding

- » The AIM Chain of CGX is based on an AIXM 5 centralized database.
- » Data4Flight®, a software that manages aeronautical data, takes advantage of digital data sets to store data according to the specified coding guidelines.

- » Thanks to the stored properties of an **Instrument Flight Procedure**, Data4Flight® generates automatically the associated **ARINC 424 procedure coding**:

Data4Flight® Procedure Encoder: Procedures edition

Ready to go to the next step.

Procedure: RNVZ6

Computation: Automatic Recomputation

Seq N*: Recompute

Edition: Parts Edition, Legs Edition

Part	Seq n°	PT	W/P Type	W/P ID	Overfly	Fix role	TD	RMD VHF Type	RMD VHF	THETA (mag)	RHO	OBD CRS val	OBD CRS type	Time	Dist	Alt DESC	Alt one	Alt two	Speed	VRT ANG	NAV PERF (Nm)	Radius	ARC CTR Type	ARC CTR ID
	10	IF	Aero Point	GIMAT		IAF										+(ABOVE LOWER)	5300 FT		220 KT					
APPROACH:GIMAT	20	TF	Aero Point	LC402	Fly By							352.05 °	TT		10.3 NM	+(ABOVE LOWER)	5300 FT		220 KT					
	30	TF	Aero Point	LC406	Fly By	IF						352.0215 °	TT		10 NM	+(ABOVE LOWER)	4000 FT		220 KT					
APPROACH:NIGLO	10	IF	Aero Point	NIGLO		IAF										+(ABOVE LOWER)	5400 FT		220 KT					
	20	TF	Aero Point	LC403	Fly By							262.22 °	TT		8.5 NM	+(ABOVE LOWER)	5400 FT		220 KT					
	30	TF	Aero Point	LC406	Fly By	IF						262.0716 °	TT		4.4 NM	+(ABOVE LOWER)	4300 FT		220 KT					
APPROACH:RIMOR	10	IF	Aero Point	RIMOR		IAF										+(ABOVE LOWER)	4000 FT		220 KT					
	20	TF	Aero Point	LC406	Fly By	IF						171.9761 °	TT		10 NM	+(ABOVE LOWER)	4000 FT		220 KT					
	10	IF	Aero Point	LC406		IF										+(ABOVE LOWER)	4000 FT		220 KT					
FINAL	20	TF	Aero Point	LC408	Fly By	FAF						262.2383 °	TT		5 NM	+(ABOVE LOWER)	4000 FT		220 KT					
	30	TF	Aero Point	LCSDF	Fly By	SDF						262.1537 °	TT		4.0825 NM	+(ABOVE LOWER)	2700 FT		185 KT					
	40	TF	Aero Point	MAPT1	Fly Over	MAPT						262.0846 °	TT		4.4019 NM	+(ABOVE LOWER)	1540 FT		185 KT					
MISSED:RIMOR	10	DF	Aero Point	LC411	Fly By														160 KT					
	20	TF	Aero Point	RIMOR	Fly By							66.1681 °	TT		13.3056 NM									

Rules validation error(s)

Criticality	Name	Data type	Identifier	Description

Revert changes Save and validate coding

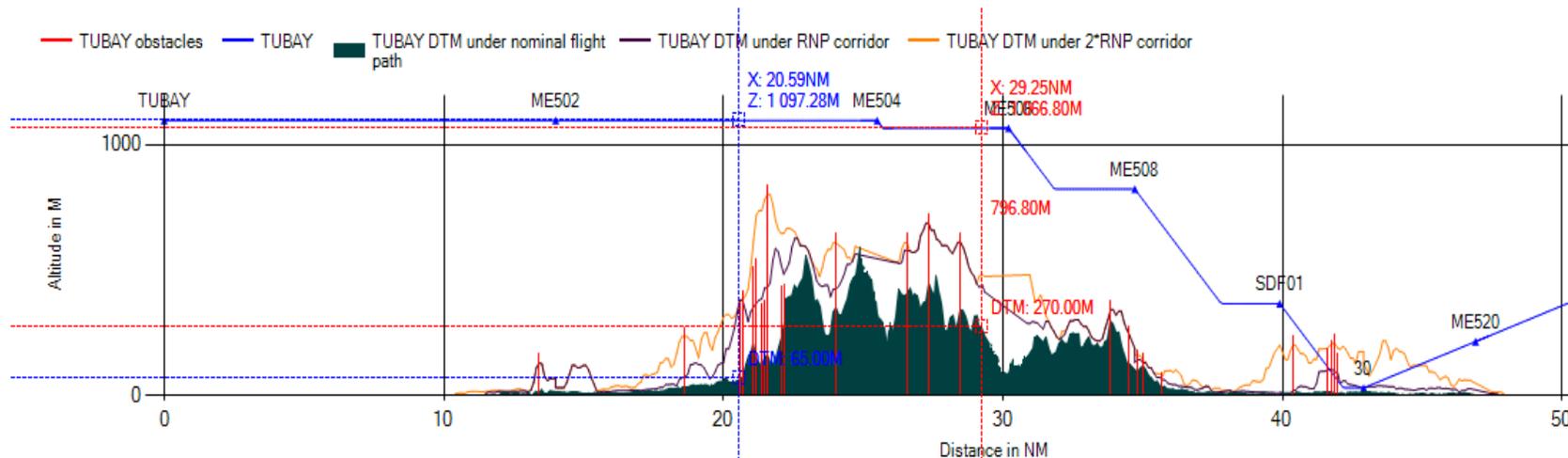
Previous Finish



Application with CGX solutions

➤ Procedure Profile

- Data4Flight® uses stored data of **Instrument Flight Procedure** to visualize the associated vertical profile.
- Profiles under the procedure protection areas and RNP corridors are also computed and visualized.

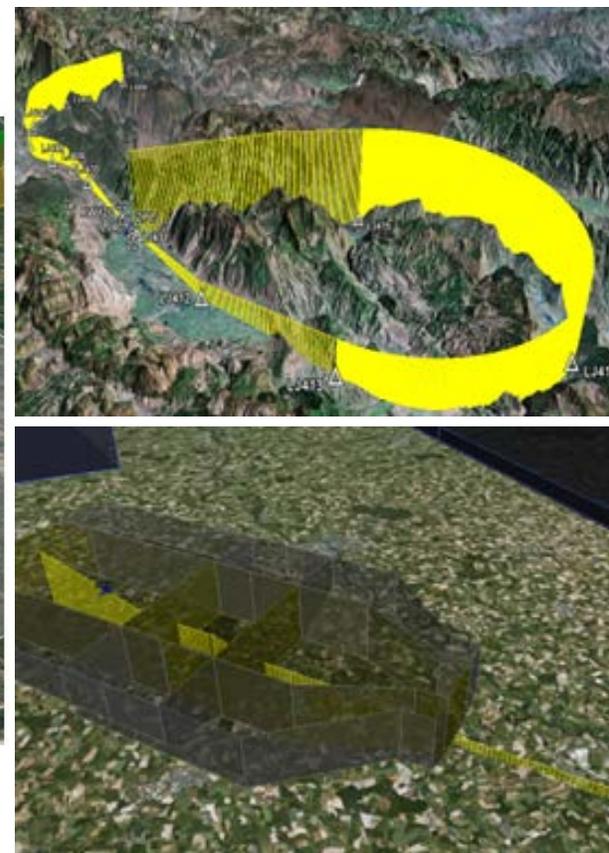
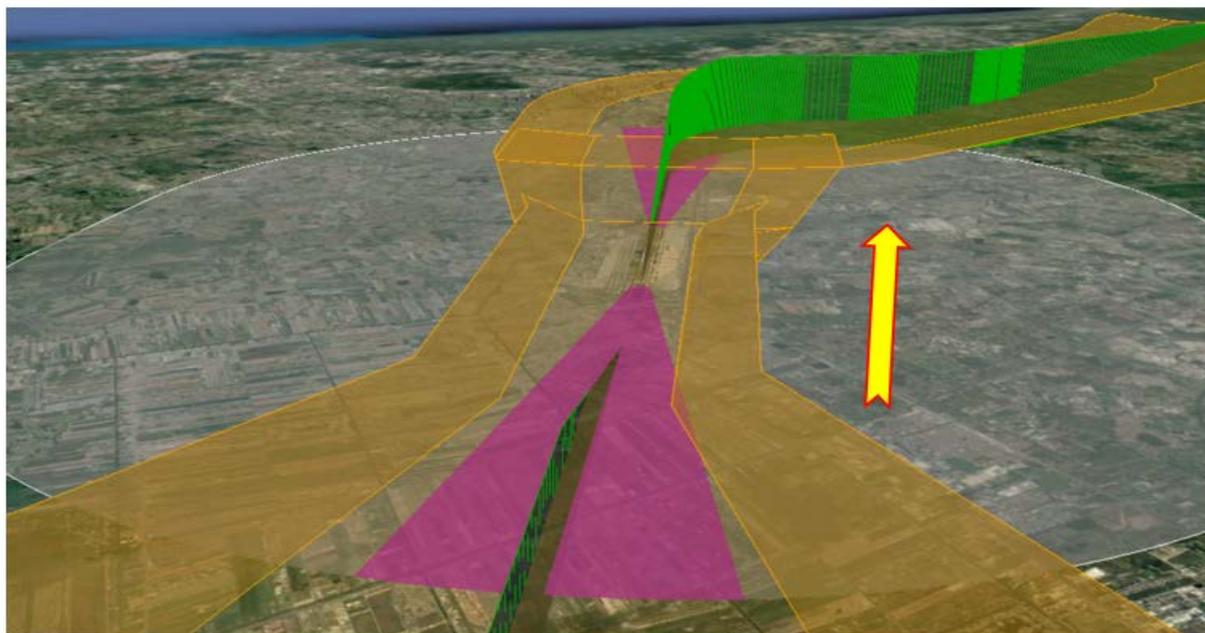




Application with CGX solutions

3D Visualization

- Having a total support of the advanced **AIXM-GML** profile, CGX tools store and computes the geometric properties of aeronautical information items and provide a 3D visualization of procedure data.





Application with CGX solutions

» Automatic reports

- » CGX solutions provide tools allowing to generate automatically the **technical report** of an **Instrument Flight Procedure**. The more the required properties are filled, the more complete the report will be, hence the advantage of using IFP digital data sets.
- » A well-informed database will benefit from CGX tools capabilities of assessment and validation against **Business Rules**. Validation results are generated in automatic reports.

Show entries

Search:

Name	Status	Integrity
1541239404 : AIXM-5.1_RULE-D8D6B -The Unit of measurement shall be specified if a value is specified for a property with uom attribute .		
C :: LDDU Taxiway:width	✓ Success	Routine
G :: LDDU Taxiway:width	✓ Success	Routine
W :: LDDU Taxiway:width	✓ Success	Routine
D :: LDDU Taxiway:width	✓ Success	Routine
F :: LDDU Taxiway:width	✓ Success	Routine
E :: LDDU Taxiway:width	✓ Success	Routine
B :: LDDU Taxiway:width	✓ Success	Routine
157383666 : AIXM-5.1_RULE-1A8520 -The feature instance actually targeted by an association (through its role name value) shall exist and correspond to the feature type defined by the model .		
APRON :: LDDU	✓ Success	Routine
1646186266 : ICAO Annex 14 AIXM-5.1_RULE-58DE0 - Runway threshold elevation for non-precision approaches shall be published with 0.5 m accuracy .		
THR :: 29 :: RWY-11/29 :: LDDU Point:horizontalAccuracy	⚠ Warning	Routine
THR :: 11 :: RWY-11/29 :: LDDU Point:horizontalAccuracy	⚠ Warning	Routine

Name Status

Showing 51 to 60 of 232 entries Previous Next



THANK YOU FOR YOUR ATTENTION

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