



The future  
of unmanned traffic  
management,  
**applied today.**

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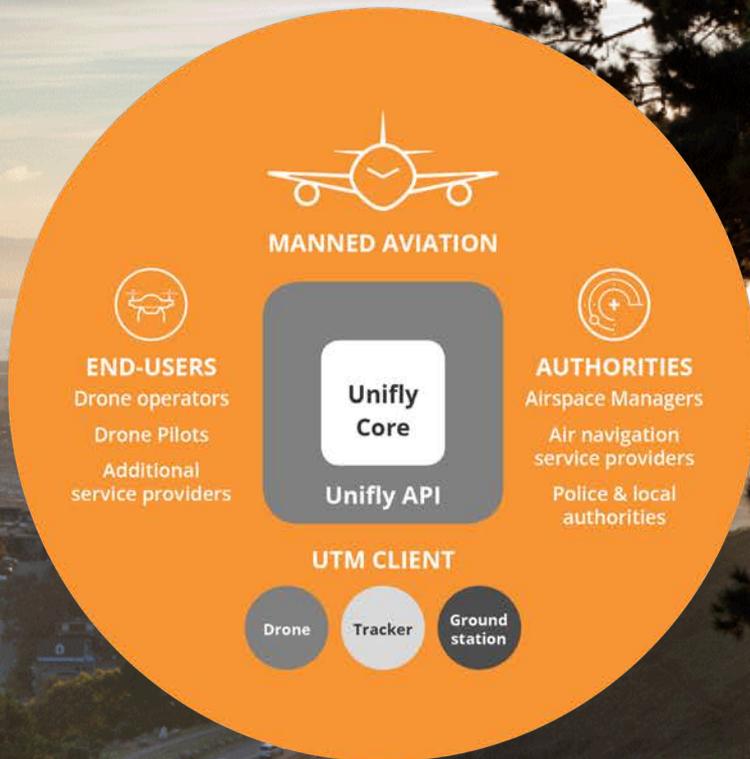
2013



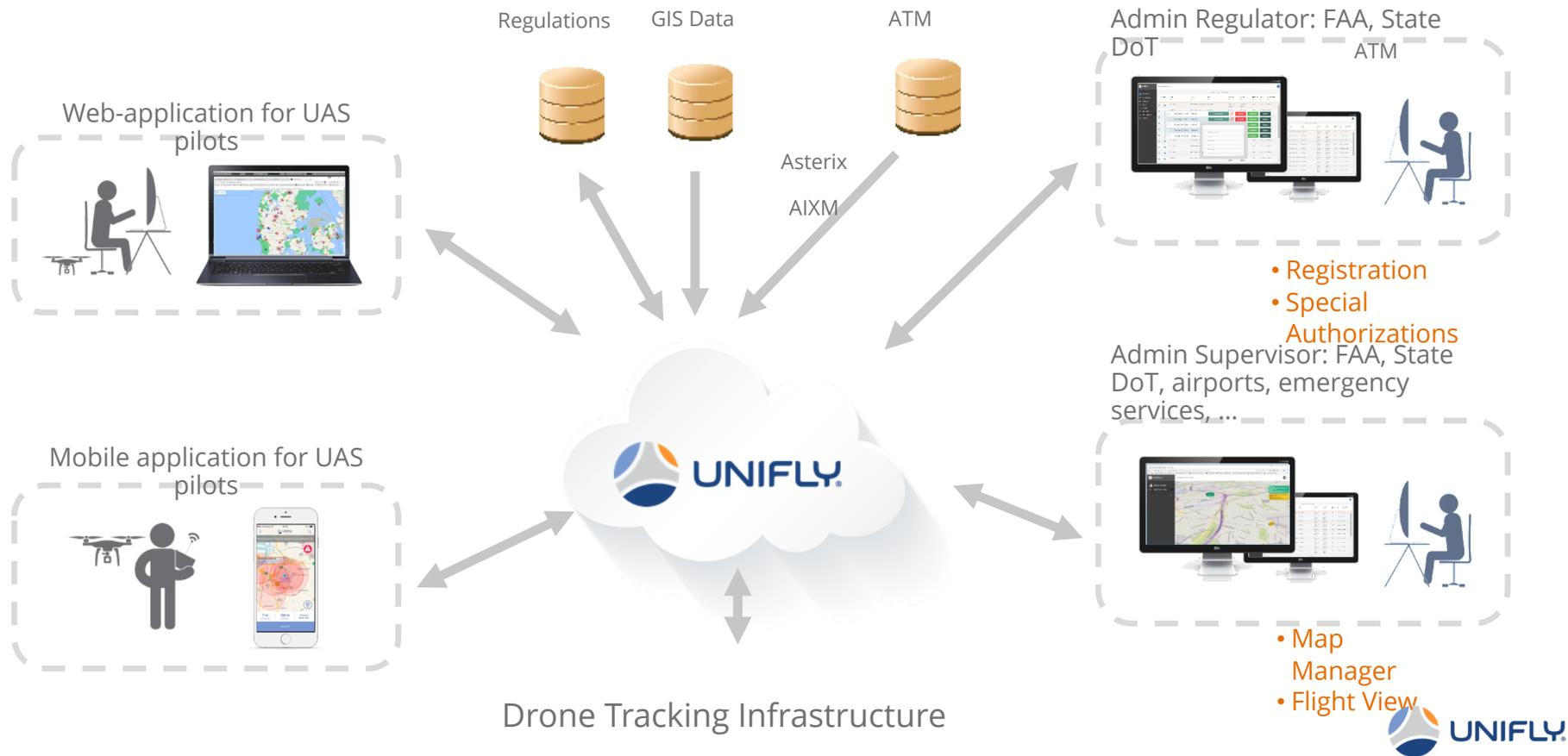
# Increase Situational Awareness

- Before flight
  - Drone pilots: State Intentions = +/- flight plan
- During Flight
  - Track position of drones
  - Track position of A/C
  - Resolve potential conflicts.
  - Communicate with Drone operators & Aircraft Pilots

# Unifly's UTM Software Architecture



# UTM solution : roles & responsibilities



# Ultimate Situational Awareness for ATC

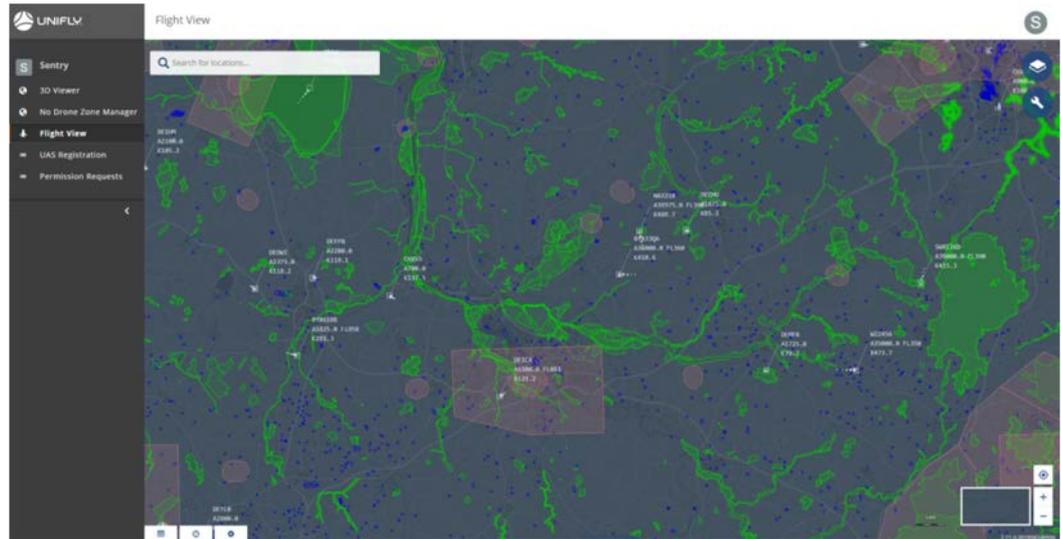
## Visualisation

- Manned
- Unmanned
- ( Dynamic ) Airspace
- No-drone Areas

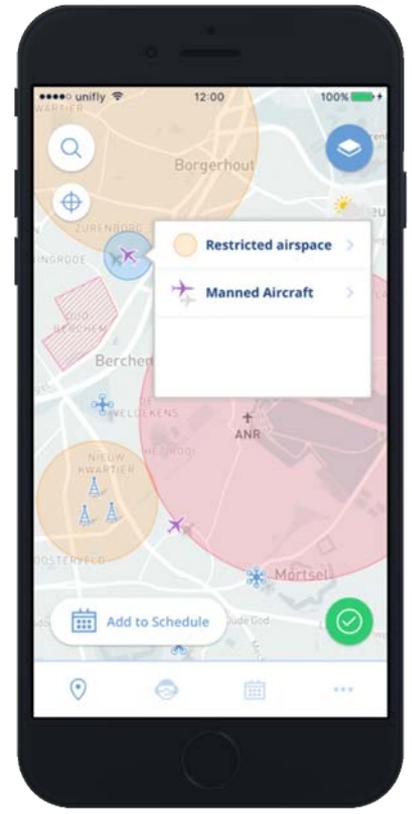
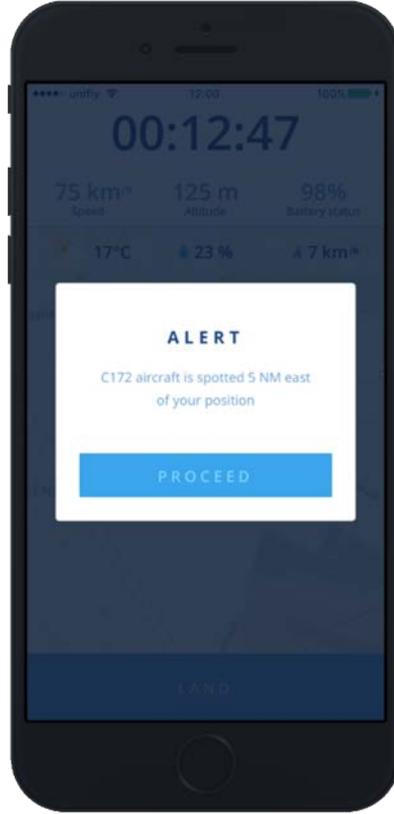
## Deconflicting

- Unmanned/Unmanned
- Unmanned/manned
- Unmanned/ No drone zones

## Replay



# Situational Awareness & Alerting for users (1)



# Situational Awareness & Alerting for users (2)

The screenshot displays a drone flight planning application. The main map shows a city area with several flight zones: a large red circle, a blue circle, a red hatched polygon, and an orange circle. A search bar at the top left contains the address "Lamorinièrestraat 161, 2018 Antwerpen". Below the search bar, there are controls for "Perimetre" (650 m), "Height" (25 m), and a "SCHEDULE FLIGHT" button. On the right side, a "Drone Details" panel provides information about the drone, including its registration number, mode-S code, squawk, brand, and model. Below this, there are sections for "Live Tracking Info", "Operator info", "Pilot Info", and "Ground Conditions".

**Drone Details**

Regref	ref3
Mode-S Code	0x123456
Type	0x123456
Model	1000

**Ground Conditions**

Temperature	10°C	Sunset	17:50:00
Wind Direction	ZW	Wind Speed	22.24 km/h
Pressure	996.28 mbar/in	Dewpoint	6°C
Precipitation Chance	36%	Visibility	No Data
KP-Index	1	Heading	ESE

# Tracking Technologies

- No “fit for all”
- Depending on the situation

Satellite

Low Power ADSB

GPS location via LTE network

FLARM

Wifi via GCS

Drone Radar

Tracking app

# Regulator's Challenge

- How do you regulate “Tracking”
- Prescriptive : Use XYZ technology
- Performance based regulation
  - situation A needs X availability / precision
  - Situation B needs Y availability / precision
  - Situation C needs Z availability / precision
- Acceptable means of compliance
- Test / Validate / Certify – e.g. NUAIR Test Site

# References: National Deployments



**DFS** Deutsche Flugsicherung

**NAVIAIR**

50 000 + registered Users

# References: Unify & Europe's U-Space

Project	Participants
	
	
	
	
	
<p>Safedrone</p>	
<p>USIS</p>	

# Refereces: Unifly's Global Reach

## Project

## Participants

 <p>Alaska-Fairbanks </p>	  
 <p>LAANC </p>	 
<p>Drone Corridor Malawi </p>	     
<p>Drone Corridor Japan </p>	  
<p>Partners</p>	    

Thank you for your  
attention

